

Irreducible homogeneous non-symmetric cones linearly isomorphic to the dual cones

By Hideyuki ISHI and Takaaki NOMURA

§1. Introduction.

In this note we present irreducible homogeneous non-symmetric open convex cones of rank 3 that are linearly isomorphic to the dual cones. As noted in [4, p. 343], if the irreducibility condition is dropped, then we have an easy example $\Omega \oplus \Omega^*$ of non-symmetric cone that is linearly isomorphic to its dual cone. One motivation of trying to find a concrete example with the property in question stems from the proof of non-selfduality of the Vinberg cone given in [2, Exercise 10, p. 21]. There one actually proves a stronger fact that the Vinberg cone is never linearly isomorphic to its dual cone, and the non-selfduality follows as a corollary. Here one wonders if there is a concretely described non-symmetric cone which is linearly isomorphic to its dual cone. In fact selfduality of a cone requires a positive definite operator which gives a linear isomorphism between the cone and its dual as in the following lemma.

Lemma 1.1. *Let Ω be an open convex cone in a real inner product vector space $(V, \langle \cdot | \cdot \rangle)$. Denote by Ω^* the dual cone of Ω defined by*

$$\Omega^* := \{y \in V ; \langle x | y \rangle > 0 \text{ for all } x \in \overline{\Omega} \setminus \{0\}\}.$$

Then, Ω is selfdual if and only if there is a positive definite operator T on V such that $\Omega^ = T(\Omega)$.*

Proof. Suppose $\Omega^* = T(\Omega)$ for some positive definite T . Then we define a new inner product in V by $\langle x | y \rangle_T := \langle Tx | y \rangle$. Let

$$\Omega_T := \{y \in V ; \langle x | y \rangle_T > 0 \text{ } (\forall x \in \overline{\Omega} \setminus \{0\})\}.$$

It is clear that $\Omega_T = T^{-1}(\Omega^*) = \Omega$. Therefore Ω is selfdual. Conversely, suppose that Ω is selfdual with respect to some inner product. Represent this inner product as the form $\langle Tx | y \rangle$ with a positive definite operator T . Then we have $\Omega = \Omega_T = T^{-1}(\Omega^*)$. \square

§2. Description of the cones.

Let \mathbf{e} be the column m -vector with the first entry equal to 1 and the others 0:

$$\mathbf{e} := \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^m.$$

Writing I_m for the m -th order identity matrix, we denote by V the vector space of matrices x of the $(m+2)$ -th order such that

$$(2.1) \quad x := \left(\begin{array}{c|cc} x_{11}I_m & x_{21}\mathbf{e} & \boldsymbol{\xi} \\ \hline x_{21}{}^t\mathbf{e} & x_{22} & x_{32} \\ \mathbf{e} & x_{32} & x_{33} \end{array} \right),$$

where $x_{ij} \in \mathbb{R}$ and $\boldsymbol{\xi} \in \mathbb{R}^m$. We note that $V \subset \text{Sym}(m+2, \mathbb{R})$. Let Ω be the cone of positive definite ones in V :

$$\Omega := \{x \in V ; x \text{ is positive definite}\}.$$

If $m = 1$, we have evidently $V = \text{Sym}(3, \mathbb{R})$, so that we assume $m \geq 2$ in what follows.

Let us show that Ω is homogeneous. To do so, we consider the following two subgroups A and N of $GL(m+2, \mathbb{R})$:

$$A := \left\{ a := \left(\begin{array}{c|cc} a_1I_m & 0 & 0 \\ \hline 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{array} \right) ; a_j > 0 \quad (j = 1, 2, 3) \right\},$$

$$N := \left\{ n := \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline n_{21}{}^t\mathbf{e} & 1 & 0 \\ \mathbf{e} & n_{32} & 1 \end{array} \right) ; n_{21}, n_{32} \in \mathbb{R}, \mathbf{n} \in \mathbb{R}^m \right\}.$$

It is clear that A normalizes N and we consider the semidirect product group $H := N \rtimes A$. We actually show that the action of H on Ω given by $H \times \Omega \ni (h, x) \mapsto \rho(h)x := hx^th$ is simply transitive. Thus given $x \in \Omega$, we just look for unique $a \in A$ and $n \in N$ so that $na^tn = x$. In view of $na^tn = \rho(na^{1/2})I_{m+2}$, we will obtain the desired simple transitivity. In order to describe the unique solution, we introduce the following polynomial functions Δ_j ($j = 1, 2, 3$) on V : for x of the form (2.1)

$$\Delta_1(x) := x_{11},$$

$$\Delta_2(x) := x_{11}x_{22} - x_{21}^2,$$

$$\Delta_3(x) := (x_{11}x_{22} - x_{21}^2)(x_{11}x_{33} - \|\boldsymbol{\xi}\|^2) - (x_{11}x_{32} - x_{21}\xi_1)^2,$$

where ξ_1 is the first entry of the vector $\boldsymbol{\xi} \in \mathbb{R}^m$ appearing in the expression (2.1) of x . Now the solution to the equation $na^t n = x$ is uniquely given by

$$\begin{aligned} a_1 &= \Delta_1(x), & a_2 &= \frac{\Delta_2(x)}{\Delta_1(x)}, & a_3 &= \frac{\Delta_3(x)}{\Delta_1(x)\Delta_2(x)}, \\ \mathbf{n} &= \frac{\boldsymbol{\xi}}{\Delta_1(x)}, & n_{21} &= \frac{x_{21}}{\Delta_1(x)}, & n_{32} &= \frac{x_{11}x_{32} - x_{21}\xi_1}{\Delta_2(x)}. \end{aligned}$$

Therefore H acts on Ω simply transitively. Note that proceeding as in [3, Theorem 2.2], we see that $\Delta_j(x)$ ($j = 1, 2, 3$) are irreducible polynomials¹.

Let us describe Ω in another way. Using an elementary determinant formula

$$\det\left(\begin{array}{c|c} A & B \\ \hline C & D \end{array}\right) = (\det A)(\det(D - CA^{-1}B)) \quad (\text{if } \det A \neq 0),$$

we see that the principal minors $\delta_j(x)$ ($j = 1, \dots, m+2$) of the matrix x in (2.1) computed by starting with (1, 1)-entry are given by

$$\delta_j(x) = \begin{cases} \Delta_1(x)^j & (1 \leq j \leq m), \\ \Delta_1(x)^{m-1}\Delta_2(x) & (j = m+1), \\ \Delta_1(x)^{m-2}\Delta_3(x) & (j = m+2). \end{cases}$$

Hence we get the following description of Ω :

$$\Omega = \{x \in V ; \Delta_1(x) > 0, \Delta_2(x) > 0, \Delta_3(x) > 0\}.$$

§3. Dual cones.

Let us introduce an inner product in V by the formula

$$(3.1) \quad \langle x | x' \rangle = x_{11}x'_{11} + x_{22}x'_{22} + x_{33}x'_{33} + 2(x_{21}x'_{21} + x_{32}x'_{32} + \boldsymbol{\xi} \cdot \boldsymbol{\xi}')$$

for $x, x' \in V$ as in (2.1), where $\boldsymbol{\xi} \cdot \boldsymbol{\xi}'$ stands for the standard inner product in \mathbb{R}^m .

Let Ω^* denote the dual cone of Ω realized in V through the inner product (3.1):

$$\Omega^* := \{x' \in V ; \langle x | x' \rangle > 0 \text{ for any } x \in \overline{\Omega} \setminus \{0\}\}.$$

Let us define a linear operator m_0 on V by

$$m_0(x) = \left(\begin{array}{c|cc} x_{33}I_m & x_{32}\mathbf{e} & \boldsymbol{\xi} \\ \hline x_{32}{}^t\mathbf{e} & x_{22} & x_{21} \\ \hline {}^t\boldsymbol{\xi} & x_{21} & x_{11} \end{array} \right) \quad (\text{for } x \text{ as in (2.1)}).$$

It is obvious that m_0^2 is the identity operator, so that m_0 is an involution. Moreover m_0 is an isometry relative to the inner product (3.1). Put $\sigma(h) := m_0\rho(h)m_0$ for

¹However, $\Delta_3(x)$ is reducible if $m = 1$, the case we have excluded.

$h \in H$. Clearly σ defines a representation of H on V . Observe that the group H is described as the set of all

$$(3.2) \quad h := \left(\begin{array}{c|cc} h_1 I_m & 0 & 0 \\ \hline h_{21} {}^t \mathbf{e} & h_2 & 0 \\ {}^t \mathbf{h} & h_{32} & h_3 \end{array} \right)$$

with $h_j > 0$ ($j = 1, 2, 3$), $h_{21} \in \mathbb{R}$, $h_{32} \in \mathbb{R}$ and $\mathbf{h} \in \mathbb{R}^m$. Then we define an involution $h \mapsto \check{h}$ in H by

$$\check{h} := \left(\begin{array}{c|cc} h_3 I_m & 0 & 0 \\ \hline h_{32} {}^t \mathbf{e} & h_2 & 0 \\ {}^t \mathbf{h} & h_{21} & h_1 \end{array} \right) \quad \text{for } h \text{ as in (3.2).}$$

By direct computation we see that this involution is an anti-automorphism.

Lemma 3.1. $\langle \rho(h)x | y \rangle = \langle x | \sigma(\check{h})y \rangle$ for any $x, y \in V$ and $h \in H$.

Proof. Since m_0 is an involutive isometry, what we have to prove is

$$(3.3) \quad \langle \rho(h)x | y \rangle = \langle m_0(x) | \rho(\check{h})m_0(y) \rangle.$$

We note that

$$\left(\begin{array}{c|cc} h_1 I_m & 0 & 0 \\ \hline h_{21} {}^t \mathbf{e} & h_2 & 0 \\ {}^t \mathbf{h} & h_{32} & h_3 \end{array} \right) = \left(\begin{array}{c|cc} h_1 I_m & 0 & 0 \\ \hline h_{21} {}^t \mathbf{e} & 1 & 0 \\ {}^t \mathbf{h} & 0 & 1 \end{array} \right) \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & h_2 & 0 \\ 0 & h_{32} & 1 \end{array} \right) \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & 1 & 0 \\ 0 & 0 & h_3 \end{array} \right)$$

and that the first and the second terms on the right hand side still decompose as follows:

$$\begin{aligned} \left(\begin{array}{c|cc} h_1 I_m & 0 & 0 \\ \hline h_{21} {}^t \mathbf{e} & 1 & 0 \\ {}^t \mathbf{h} & 0 & 1 \end{array} \right) &= \left(\begin{array}{c|cc} h_1 I_m & 0 & 0 \\ \hline 0 & 1 & 0 \\ 0 & 0 & 1 \end{array} \right) \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline h_{21} {}^t \mathbf{e} & 1 & 0 \\ 0 & 0 & 1 \end{array} \right) \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & 1 & 0 \\ {}^t \mathbf{h} & 0 & 1 \end{array} \right), \\ \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & h_2 & 0 \\ 0 & h_{32} & 1 \end{array} \right) &= \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & h_2 & 0 \\ 0 & 0 & 1 \end{array} \right) \left(\begin{array}{c|cc} I_m & 0 & 0 \\ \hline 0 & 1 & 0 \\ 0 & h_{32} & 1 \end{array} \right). \end{aligned}$$

Since $h \mapsto \check{h}$ is an anti-automorphism, it is enough to prove (3.3) for each of these pieces. We omit the details of simple computations. \square

Theorem 3.2. One has $\Omega^* = m_0(\Omega)$.

Proof. Any $x \in \overline{\Omega}$ is a positive semidefinite matrix, so that $\langle x | I_{m+2} \rangle = x_{11} + x_{22} + x_{33} > 0$ if $x \neq 0$. Thus $I_{m+2} \in \Omega^*$. By Lemma 3.1, this implies $\Omega^* = \sigma(H)I_{m+2}$. Since

$$\sigma(H)I_{m+2} = (m_0 \rho(H) m_0)(I_{m+2}) = m_0(\rho(H)I_{m+2}) = m_0(\Omega),$$

we get $\Omega^* = m_0(\Omega)$. \square

Asano's criterion [1, Theorem 4] says that our cone Ω is irreducible, and Vinberg's criterion [5, Proposition 3, p. 73] together with the classification of irreducible symmetric cones tells us that Ω is not symmetric. Hence our cone is an irreducible non-symmetric cone that is linearly isomorphic to Ω^* .

References

- [1] H. Asano, *On the irreducibility of homogeneous convex cones*, J. Fac. Sci. Univ. Tokyo, **15** (1968), 201–208.
- [2] J. Faraut and A. Korányi, *Analysis on symmetric cones*, Clarendon Press, Oxford, 1994.
- [3] H. Ishi, *Basic relative invariants associated to homogeneous cones and applications*, J. Lie Theory, **11** (2001), 155–171.
- [4] E. B. Vinberg, *The theory of convex homogeneous cones*, Trans. Moscow Math. Soc., **12** (1963), 340–403.
- [5] E. V. Vinberg, *The structure of the group of automorphisms of a homogeneous convex cone*, Trans. Moscow Math. Soc., **13** (1965), 63–93.

GRADUATE SCHOOL OF MATHEMATICS, NAGOYA UNIVERSITY, CHIKUSA-KU 464-8602, NAGOYA, JAPAN

E-mail address: `hideyuki@math.nagoya-u.ac.jp`

FACULTY OF MATHEMATICS, KYUSHU UNIVERSITY, HIGASHI-KU 812-8581, FUKUOKA, JAPAN

E-mail address: `tnomura@math.kyushu-u.ac.jp`