Right Multiplication Operators in the Clan Structure of a Euclidean Jordan Algebra

Takaaki NOMURA (Kyushu University)

Tambov University, Russia April 22, 2009

Homogeneous Open Convex Cones

V: a real vector space with an inner product $V \supset \Omega$: a <u>regular</u> open convex cone (<u>contains no entire line</u>)

- $G(\Omega) := \{g \in GL(V) ; g(\Omega) = \Omega\}$: linear automorphism group of Ω This is a Lie group as a closed subgroup of GL(V).
- Ω is homogeneous $\iff G(\Omega) \frown \Omega$ is transitive

 $\begin{array}{lll} \textbf{Example:} \ V = \operatorname{Sym}(r,\mathbb{R}) \supset \Omega := \operatorname{Sym}(r,\mathbb{R})^{++} : \\ GL(r,\mathbb{R}) \frown \Omega \quad \text{by} \quad GL(r,\mathbb{R}) \times \Omega \ni (g,x) \mapsto gx^tg \in \Omega \end{array}$

This is a selfdual homogeneous open convex cone (symmetric cone). Ω is selfdual $\stackrel{\text{def}}{\iff} \exists \langle \cdot | \cdot \rangle$ s.t. $\Omega = \{y \in V ; \langle x | y \rangle > 0 \ (\forall x \in \overline{\Omega} \setminus \{0\})\}$ (the RHS is the dual cone taken relative to $\langle \cdot | \cdot \rangle$)

 $\mathbf{2}$

Symmetric Cones \rightleftharpoons Euclidean Jordan Algebras

 $\Omega \rightleftharpoons V$: algebraic str. in the ambient VS (\equiv tangent space at a ref. pt.)

- V with a bilinear product xy is called a Jordan algebra if for all x, y ∈ V
 (1) xy = yx,
 (2) x²(xy) = x(x²y).
- A real Jordan algebra is said to be Euclidean if $\exists \langle \cdot | \cdot \rangle$ s.t. $\langle xy | z \rangle = \langle x | yz \rangle$ ($\forall x, y$)

List of Irreducible Symmetric Cones:

$$\Omega = \operatorname{Sym}(r, \mathbb{R})^{++} \subset V = \operatorname{Sym}(r, \mathbb{R}), \quad A \circ B := \frac{1}{2}(AB + BA)$$

$$\Omega = \operatorname{Herm}(r, \mathbb{C})^{++} \subset V = \operatorname{Herm}(r, \mathbb{C})$$

$$\Omega = \operatorname{Herm}(r, \mathbb{H})^{++} \subset V = \operatorname{Herm}(r, \mathbb{H})$$

$$\Omega = \operatorname{Herm}(3, \mathbb{O})^{++} \subset V = \operatorname{Herm}(3, \mathbb{O})$$

$$\Omega = \Lambda_n \subset V = \mathbb{R}^n \text{ (n-dimensional Lorentz cone)}$$

By Vinberg's theory (1963)

Homogeneous Open Convex Cones \rightleftharpoons Clans with unit element $\Omega \rightleftharpoons V$: algebraic str. in the ambient VS (\equiv tangent space at a ref. pt.)

• The Case of Symmetric Cones: $G(\Omega)$ is reductive.

<u>JA str. of V</u>: $V \equiv T_e(\Omega) \equiv \mathfrak{p}$ of the Cartan decomposition $\mathfrak{g}(\Omega) = \mathfrak{k} + \mathfrak{p}$ Indeed $\mathfrak{p} = \{M(x) ; x \in V\}$. (The Jordan product is commutative.)

• The Case of General Homogeneous Convex Cones:

simply transitive action of Iwasawa subgroup of $G(\Omega)$

<u>Clan str. of V</u>: $V \equiv T_e(\Omega) \equiv$ Iwasawa subalgebra $\mathfrak{s} := \mathfrak{a} + \mathfrak{n}$ of $\mathfrak{g}(\Omega)$ Indeed $\mathfrak{s} = \{L(x) ; x \in V\}$. (The clan product is non-commutative, in general.) H is a split solvable Lie group, acting simply transitively on $\Omega.$

a function f on Ω , is relatively invariant (w.r.t. H) $\stackrel{\text{def}}{\iff} \exists \chi$: 1-dim. rep. of H s.t. $f(gx) = \chi(g)f(x)$ (for all $g \in H, x \in \Omega$).

Theorem [Ishi 2001]. $\exists \Delta_1, \ldots, \Delta_r \ (r := \operatorname{rank}(\Omega)):$ relat. inv. <u>irred</u>. polynomial functions on V s.t any relat. inv. polynomial function P(x) on V is written as $P(x) = c \Delta_1(x)^{m_1} \cdots \Delta_r(x)^{m_r} \quad (c = \operatorname{const.}, \ (m_1, \ldots, m_r) \in \mathbb{Z}_{\geq 0}^r).$

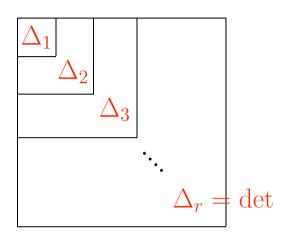
Theorem [Ishi–N. 2008].

W: the complexification of the clan $V, \ensuremath{\boldsymbol{\mathcal{W}}}$

 $R(\boldsymbol{w}):$ the right multiplication operator by \boldsymbol{w} in \boldsymbol{W}

 \implies irreducible factors of det R(w) are just $\Delta_1(w), \ldots, \Delta_r(w)$.

Example: $\Omega = \operatorname{Sym}(r, \mathbb{R})^{++} \subset V = \operatorname{Sym}(r, \mathbb{R})$



• Product in V as a clan: $x \Delta y = \underline{x} y + y^{t}(\underline{x})$, where for $x = (x_{ij}) \in \text{Sym}(r, \mathbb{R})$,

we put
$$\underline{x} := \int_{j} \begin{pmatrix} \frac{1}{2}x_{11} & & 0 \\ & \frac{1}{2}x_{22} & & \\ & & \ddots & \\ & & & x_{ji} & \ddots & \\ & & & & \frac{1}{2}x_{nn} \end{pmatrix} (i < j).$$
 Thus $x = \underline{x} + {}^{t}(\underline{x}).$

In this case we have $\det R(y) = \Delta_1(y) \cdots \Delta_r(y)$.

The case of general irreducible symmetric cone $\Omega \subset V$

V: a simple Euclidean Jordan algebra of rank r with unit element e_i $\Omega := \text{Int}\{x^2 ; x \in V\}$: the symmetric cone in V, $G := G(\Omega)^{\circ}$: the connected component of $G(\Omega)$, $\mathfrak{g} := \operatorname{Lie}(G), \mathfrak{k} := \operatorname{Der}(V), \mathfrak{p} := \{M(x) ; x \in V\}.$ Then $\mathfrak{g} = \mathfrak{k} + \mathfrak{p}$ is a Cartan decomposition of \mathfrak{g} with $\theta X = -{}^t X$, We fix $\begin{cases} \langle x | y \rangle := \operatorname{tr}(xy): \text{ the trace inner product of } V, \\ c_1, \dots, c_r: \text{ a Jordan frame of } V, \text{ so that } c_1 + \dots + c_r = e. \end{cases}$ $V = \bigoplus V_{jk}$: the corresponding Peirce decomposition, where $1 \leq i \leq k \leq r$ $V_{ij} := \mathbb{R}c_j \qquad (j = 1, \dots, r),$ $V_{ik} := \{ x \in V ; \ M(c_i)x = \frac{1}{2}(\delta_{ij} + \delta_{ik})x \quad (i = 1, 2, \dots, r) \} \quad (1 \le j < k \le r).$ $\mathfrak{a} := \mathbb{R}M(c_1) \oplus \cdots \oplus \mathbb{R}M(c_r)$: maximal abelian in \mathfrak{p} , $\alpha_1, \ldots, \alpha_r$: basis of \mathfrak{a}^* dual to $M(c_1), \ldots, M(c_r)$. Then the positve \mathfrak{a} -roots are $\frac{1}{2}(\alpha_k - \alpha_j)$ (j < k), the corresponding root spaces are described as

$$\begin{split} \mathfrak{n}_{kj} &:= \mathfrak{g}_{(\alpha_k - \alpha_j)/2} = \{ z \square c_j \; ; \; z \in V_{jk} \} \quad (a \square b := M(ab) + [M(a), M(b)]). \\ \text{With } \mathfrak{n} &:= \sum_{j < k} \mathfrak{n}_{kj}, \text{ we get lwasawa decomposition } \mathfrak{g} = \mathfrak{k} \oplus \mathfrak{a} \oplus \mathfrak{n}. \\ \text{Let } A &:= \exp \mathfrak{a}, \; N := \exp \mathfrak{n}. \\ \text{Then } H &:= N \rtimes A \text{ acts on } \Omega \text{ simply transitively, so that we have an diffeomorphism} \\ H &\ni h \mapsto he \in \Omega. \end{split}$$

This gives rise to a linear isomorphism $\mathfrak{h} := \operatorname{Lie}(H) \ni X \mapsto Xe \in V$. Its inverse map is denoted as $V \ni v \mapsto X_v \in \mathfrak{h}$, so that $X_ve = v$. Now the clan \triangle product in V is by definition

$$v_1 \triangle v_2 := X_{v_1} v_2 = R(v_2) v_1.$$

Lemma. (1) If $v = a_1c_1 + \cdots + a_rc_r$ $(a_j \in \mathbb{R}, \ldots, a_r \in \mathbb{R})$, then $X_v = M(v)$. (2) If $v \in V_{jk}$ (j < k), then $X_v = 2(v \Box c_j)$.

Let
$$\Xi := V_{1r} \oplus \cdots \oplus V_{r-1,r}$$
.

$$\begin{array}{c|c} \mathbb{R}c_1 & & \\ & & & \\ & & \\ & & \\ & & \\ & & & \\ & &$$

$$W := \Xi \oplus \mathbb{R}c_r, \quad V' := \bigoplus_{1 \le i \le j \le r-1} V_{ij}$$

Proposition. W is a two-sided ideal in the clan V: $X_v(W) \subset W, \qquad R_v(W) \subset W \qquad (\forall v \in V).$

In what follows, we put $X_v^W := X_v \big|_W$, $R_v^W := R_v \big|_W$. Then

Corollary. By writing
$$v \in V$$
 as $v = v' + w$ $(v' \in V', w \in W)$, the operator R_v is of the form $R_v = \left(\frac{R'_{v'} \mid O}{* \mid R_v^W}\right)$.

Analysis of R_v^W

Recall $V' = V_0(c_r)$, $\Xi = V_{1/2}(c_r)$, the Peirce 0- and 1/2- spaces respectively. The Jordan subalgebra V' has a representation ϕ on Ξ : given by $\phi(v')\xi = 2v'\xi$. $\phi: V' \to \operatorname{End}(\Xi)$ satisfies: (1) $\phi(e') = \operatorname{Id}_{\Xi} (e' := c_1 + \dots + c_{r-1})$, (2) $\phi(v'_1v'_2) = \frac{1}{2} (\phi(v'_1)\phi(v'_2) + \phi(v'_2)\phi(v'_1))$.

On the other hand, if $v' \in V'$, we have $R_{v'}(\Xi) \subset \Xi$, so that we set $R_{v'}^{\Xi} := R_{v'}|_{\Xi}$.

Proposition. $R_{v'}^{\Xi} = \phi(v')$.

Proposition. By writing $v \in V$ as $v = v' + \xi + v_r c_r$ ($v' \in V'$, $\xi \in \Xi$, $v_r \in \mathbb{R}$), the operator R_v^W is of the form $R_v^W = \left(\frac{\phi(v') | \frac{1}{2} \langle \cdot | c_r \rangle \xi}{\langle \cdot | \xi \rangle c_r | v_r I_{\mathbb{R}c_r}}\right).$

We renormalize the inner product in $W = \Xi + \mathbb{R}c_r$:

$$\langle \, \eta + y_r c_r \, | \, \eta' + y_r' c_r \,
angle_W = \langle \, \eta \, | \, \eta' \,
angle + rac{1}{2} y_r y_r' \qquad (\eta, \eta' \in \Xi \, \, ext{and} \, \, y_r, y_r' \in \mathbb{R}).$$

Then we have a more comfortable expression:

$$R_v^W = \left(\frac{\phi(v')}{\langle \cdot |\xi \rangle_W c_r} | \frac{\langle \cdot |c_r \rangle_W \xi}{v_r I_{\mathbb{R}c_r}}\right) \qquad (v = v' + \xi + v_r c_r)$$

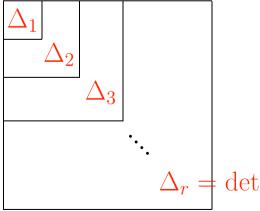
Jordan algebra principal minors

Jordan frame c_1, \ldots, c_r gives

$$\mathbb{R}c_1 = V^{(1)} \subset V^{(2)} \subset \cdots \subset V^{(r)} = V, \quad V^{(k)} := \bigoplus_{1 \le i \le j \le k} V_{ij}$$

det^(k): the determinant of the Jordan algebra $V^{(k)}$, $P^{(k)}$: the orthogonal projector $V \to V^{(k)}$, $\Delta_k(x) := \det^{(k)}(P_k x)$: the k-th Jordan algebra prioncipal minor.

Fact. $\Delta_1, \ldots, \Delta_r$ are the basic relative invariants associated to the symmetric cone Ω of V.



Theorem. det $R(v) = \Delta_1(v)^d \cdots \Delta_{r-1}(v)^d \Delta_r(v)$, where $d = \text{common dimension of } V_{ij} \ (i < j)$.

d = 1 for $\operatorname{Sym}(r, \mathbb{R})$, $d = \dim_{\mathbb{R}} \mathbb{K}$ for $\operatorname{Herm}(r, \mathbb{K})$ $(\mathbb{K} = \mathbb{C}, \mathbb{H}, \mathbb{O})$, r = 2, d = n - 2 for $\Omega = \Lambda_n$ $(n \ge 3)$.

The formula is nice in view of dim $V = r + \frac{d}{2} \cdot r(r-1)$, because $\deg(\Delta_1(v)^d \cdots \Delta_{r-1}(v)^d \Delta_r(v)) = d(1 + \cdots + (r-1)) + r = r + \frac{d}{2} \cdot r(r-1).$

Non-selfdual Irreducible Homogeneous Convex Cones linearly isomorphic to the dual cones

- Ω is selfdual $\iff \exists T$: positive definite selfadjoint operator s.t. $T(\Omega) = \Omega^*$ $\left(\Omega^* := \left\{ y \in V \; ; \; \langle x \, | \, y \, \rangle > 0 \quad \text{for } \forall x \in \overline{\Omega} \setminus \{0\} \right\} \right)$
- Even though there is no positive definite selfadjoint operator T s.t. $T(\Omega) = \Omega^*$, we might find such T if we do not require the positive definiteness.
- If one accepts reducible ones, then $\Omega_0 \oplus \Omega_0^*$ just gives an example. Thus the irreducibility counts for much here.
- The list in [Kaneyuki–Tsuji] of irreducible homogeneous open convex cones $(\dim \le 10)$ is described up to linear isomoprhisms. There is one non-selfdual irreducible homogeneous convex cone (7-dimensional) identified with its dual cone.
- In an exercise of Faraut–Korányi's book, a hint is given to prove that the Vinberg cone is never linerly isomorphic to its dual cone. Then the non-selfduality follows from this immediately.

We assume
$$m \geq 1$$
.

$$e := \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \in \mathbb{R}^{m+1}, \quad I_{m+1}: (m+1) \times (m+1) \text{ unit matrix}$$

$$V := \begin{cases} x := \begin{pmatrix} \frac{x_1 I_{m+1} \mid \boldsymbol{e}^{t} \boldsymbol{x}' \mid \boldsymbol{\xi}}{\boldsymbol{x}' \mid \boldsymbol{e} \mid \boldsymbol{X} \mid \boldsymbol{x}''} \\ \frac{t}{\boldsymbol{\xi}} \mid \frac{t}{\boldsymbol{x}'' \mid \boldsymbol{x}_2} \end{pmatrix}; \quad x_1 \in \mathbb{R}, \quad x_2 \in \mathbb{R}, \quad X \in \operatorname{Sym}(m, \mathbb{R}) \\ \boldsymbol{\xi} \in \mathbb{R}^{m+1}, \quad \boldsymbol{x}' \in \mathbb{R}^m, \quad \boldsymbol{x}'' \in \mathbb{R}^m \end{cases}$$

We note $V \subset \text{Sym}(2m+2, \mathbb{R})$, and take $\Omega := \{x \in V ; x \gg 0\}$.

When
$$m = 1$$
, we have $x = \begin{pmatrix} x_1 & 0 & x' & \xi_1 \\ 0 & x_1 & 0 & \xi_2 \\ x' & 0 & X & x'' \\ \xi_1 & \xi_2 & x'' & x_2 \end{pmatrix}$.

Homogeneity of Ω

$$\mathbf{H} := \left\{ h := \begin{pmatrix} \frac{h_1 I_{m+1} \mid 0 \quad 0}{\mathbf{h}'^t \mathbf{e} \mid H \quad 0} \\ \frac{t_1 \mathbf{c}}{\mathbf{c}} \mid \mathbf{c} \mid \mathbf{h}' \mid \mathbf{h}_2 \end{pmatrix} ; \begin{array}{c} h_j > 0 \ (j = 1, 2), \ \mathbf{h}' \in \mathbb{R}^m, \ \mathbf{h}'' \in \mathbb{R}^m \\ \boldsymbol{\zeta} \in \mathbb{R}^{m+1}, H \in GL(m, \mathbb{R}) \end{cases} \right\}$$

H acts on Ω by $\mathbf{H} \times \Omega \ni (h, x) \mapsto hx^th$. The action is in fact simply transitive. We have $\mathbf{H} = \mathbf{N} \rtimes \mathbf{A}$ with

$$\mathbf{A} := \left\{ \begin{aligned} a &:= \begin{pmatrix} \underline{a_1 I_{m+1}} & 0 & 0 \\ 0 & | & A & 0 \\ 0 & | & 0 & a_2 \end{pmatrix} \\ \mathbf{N} &:= \left\{ n &:= \begin{pmatrix} \underline{I_{m+1}} & 0 & 0 \\ \mathbf{n'' e} & | & N & 0 \\ \mathbf{\nu} & | \mathbf{n''' 1} \end{pmatrix} \\ \mathbf{N} &:= \left\{ n &:= \begin{pmatrix} \underline{I_{m+1}} & 0 & 0 \\ \mathbf{n'' e} & | & N & 0 \\ \mathbf{\nu} & | \mathbf{n''' 1} \end{pmatrix} \\ \mathbf{N} &:= \begin{bmatrix} \mathbf{n'' e} & N & 0 \\ \mathbf{n'' e} & | & \mathbf{n'' 1} \end{bmatrix} \\ \mathbf{N} &:= \begin{bmatrix} \mathbf{n'' e} & N & 0 \\ \mathbf{n'' e} & | & \mathbf{n'' 1} \end{bmatrix} \\ \mathbf{N} &:= \begin{bmatrix} \mathbf{n'' e} & \mathbf{n'' 1} \\ \mathbf{n'' e} & | & \mathbf{n'' 1} \end{bmatrix} \\ \mathbf{N} &:= \begin{bmatrix} \mathbf{n'' e} & \mathbf{n'' 1} \\ \mathbf{n'' e} & \mathbf{n'' 1} \end{bmatrix} \\ \mathbf{N} &:= \begin{bmatrix} \mathbf{n'' e} & \mathbf{n'' 1} \\ \mathbf{n'' e} & \mathbf{n'' 1} \end{bmatrix} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n'' e} & \mathbf{n'' e} \end{bmatrix} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n'' e} & \mathbf{n'' e} \end{bmatrix} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n'' e} & \mathbf{n'' e} \end{bmatrix} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n'' e} &: \mathbf{n'' e} \end{bmatrix} \\ \mathbf{n'' e} &: \mathbf{n'' e} \\ \mathbf{n''$$

In solving $x = na^t n$ ($x \in \Omega$: given) we obtain basic relative invariants.

Basic relative invariants: For x

$$m{x} = egin{pmatrix} x_1 I_{m+1} & m{e} \ ^t m{x}' \ m{\xi} \ ^t m{e} & X \ m{x}'' \ ^t m{e} & X \ m{x}'' \ m{x}' \ m{x}'' \ m{x}_2 \end{pmatrix} \in V,$$

$$\Delta_{1}(x) := x_{1},$$

$$\Delta_{j}(x) := \det\left(\frac{x_{1} | {}^{t}\boldsymbol{x}_{j-1}'|}{\boldsymbol{x}_{j-1}'| X_{j-1}}\right) \qquad (j = 2, \dots, m+1)$$

$$\left(X_{k} := \begin{pmatrix}x_{11} \cdots x_{k1}\\ \vdots & \vdots\\ x_{k1} \cdots & x_{kk}\end{pmatrix}, \quad \boldsymbol{x}_{k}' := \begin{pmatrix}x_{1}'\\ \vdots\\ x_{k}'\end{pmatrix} \in \mathbb{R}^{k}\right),$$

$$\Delta_{m+2}(x) := x_{1} \det\left(\begin{array}{c}x_{1} | {}^{t}\boldsymbol{x}' & \xi_{1}\\ \boldsymbol{x}' | X & \boldsymbol{x}''\\ \xi_{1} | {}^{t}\boldsymbol{x}'' & x_{2}\end{array}\right) - \left(\|\boldsymbol{\xi}\|^{2} - \xi_{1}^{2}\right) \det\left(\frac{x_{1} | {}^{t}\boldsymbol{x}'}{\boldsymbol{x}'| X}\right)$$

$$\left({}^{t}\boldsymbol{\xi} = (\xi_{1}, \dots, \xi_{m+1})\right).$$

Note $\deg \Delta_{m+2} = m+3$.

Inner product in V: For
$$x = \begin{pmatrix} x_1 I_{m+1} & \boldsymbol{e}^{t} \boldsymbol{x}' & \boldsymbol{\xi} \\ \boldsymbol{x}' & \boldsymbol{e} & \boldsymbol{X} & \boldsymbol{x}'' \\ \boldsymbol{t} \boldsymbol{\xi} & \boldsymbol{t} \boldsymbol{x}'' & \boldsymbol{x}_2 \end{pmatrix}$$
, $y = \begin{pmatrix} y_1 I_{m+1} & \boldsymbol{e}^{t} \boldsymbol{y}' & \boldsymbol{\eta} \\ \boldsymbol{y}' & \boldsymbol{e} & \boldsymbol{Y} & \boldsymbol{y}'' \\ \boldsymbol{t} \boldsymbol{\eta} & \boldsymbol{t} \boldsymbol{y}'' & \boldsymbol{y}_2 \end{pmatrix}$
 $\langle x \mid y \rangle := x_1 y_1 + \operatorname{tr}(XY) + x_2 y_2 + 2(\boldsymbol{x}' \cdot \boldsymbol{y}' + \boldsymbol{x}'' \cdot \boldsymbol{y}'' + \boldsymbol{\xi} \cdot \boldsymbol{\eta})$

We consider the dual cone Ω^* taken with respect to this inner product: $\Omega^* := \{ y \in V ; \langle x | y \rangle > 0 \text{ for } \forall x \in \overline{\Omega} \setminus \{0\} \}.$

Define a linear operator
$$T_0$$
 on V by $T_0 x = \begin{pmatrix} x_2 I_{m+1} & e^{t} x'' J & \xi \\ J x'' & t e & J X J & J x' \\ t \xi & t x' J & x_1 \end{pmatrix}$ $(x \in V)$,
where $J \in \operatorname{Sym}(m, \mathbb{R})$ is given by $J = \begin{pmatrix} 0 & 1 \\ & \ddots & \\ 1 & & 0 \end{pmatrix}$.

Theorem [Ishi-N. 2009]. $\Omega^* = T_0(\Omega)$.

For
$$h := \begin{pmatrix} h_1 I_{m+1} & 0 & 0 \\ h'^t e & H & 0 \\ {}^t \zeta & {}^t h'' & h_2 \end{pmatrix} \in \mathbf{H}$$
, we set $\check{h} := \begin{pmatrix} h_2 I_{m+1} & 0 & 0 \\ J h''^t e & J^t H J & 0 \\ {}^t \zeta & {}^t h' J & h_1 \end{pmatrix}$.

Then $h \mapsto \check{h}$ is an involutive anti-automorphism of **H**.

$$\rho(h)x := hx^{t}h \ (h \in \mathbf{H}, x \in \Omega), \qquad \sigma(h) := T_{0}\rho(h)T_{0} \ (h \in \mathbf{H}).$$

Lemma. $\langle \rho(h)x | y \rangle = \langle x | \sigma(\check{h})y \rangle \quad (x, y \in V, h \in \mathbf{H}).$

Conjecture. Ω with rank $\Omega = r$ is selfdual \iff the degrees of basic relative invariants associated to Ω and Ω^* are both $1, 2, \ldots, r$.