Homogeneous Convex Cones and Basic Relative Invariants

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25 November 2013

- Homogeneous convex cones provide
 - many examples of non-reductive prehomogeneous vector spaces
 - \rightsquigarrow important to know the basic relative invariants
- Applications to statistics (from positive-definite matrices to general convex cones)
- Matrix realizations of interesting homogeneous convex cones

By Vinberg (1963), homogeneous cones are sets of matrices of the form TT^* , where T's are regular upper triangular matrices from some non-associative algebras.

 \circ beautiful in theory but hard to handle in practice

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Homogeneous convex cones

 $\begin{array}{l} V: \text{ a real vector space } (\dim V < \infty) \\ V \supset \Omega: \text{ a regular open convex cone (containing no entire line)} \\ GL(\Omega) := \{g \in GL(V) \; ; \; g(\Omega) = \Omega\}: \text{ the linear automorphism group of } \Omega \\ & (\text{a Lie group as a closed subgroup of } GL(V)) \\ \Omega \text{ is homogeneous } \stackrel{\text{def}}{\iff} GL(\Omega) \frown \Omega \text{ is transitive.} \end{array}$

Vinberg (1963)

homogeneous (regular affine) convex domain \Rightarrow algebraic structure of the ambient vector space (\equiv tangent space of a reference point)

Algebras associated to homogeneous convex domains (Vinberg 1963)

$$\begin{array}{ll}V \text{ is a real VS with a bilinear product } x \bigtriangleup y = L(x)y.\\ V \text{ is a clan } & \stackrel{\text{def}}{\Longrightarrow}\\ (1) \ [L(x), L(y)] = L(x \bigtriangleup y - y \bigtriangleup x) & (\text{left symmetric algebra}),\\ (2) \ \exists s \in V^* \text{ s.t. } s(x \bigtriangleup y) \text{ is an onner pruduct of } V & (\text{compact}),\\ (3) \ \text{Each } L(x) \text{ has only real eigenvalues} & (\text{normal}). \end{array}$$

- clans with unit element \longleftrightarrow homogeneous convex cones.
- homogeneous convex cones \Longrightarrow clans

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- $\exists H$: a split solvable subgroup of $GL(\Omega)$ s.t. $H \curvearrowright \Omega$ simply transitively. \rightsquigarrow Fixing $E \in \Omega$, we have $H \approx HE = \Omega$ (diffeo)
- $\rightsquigarrow \mathfrak{h} := \operatorname{Lie}(H) \cong T_E(\Omega) \equiv V$ (linear isomorphism obtained by differentiation) $\rightsquigarrow \forall x \in V, \exists 1T \in \mathfrak{h} \text{ s.t. } TE = x.$
- \rightsquigarrow Writing T = L(x), we define a product \triangle by $x \triangle y := L(x)y$. E is a unit element.

• symmetric cone $\Omega \rightleftharpoons$ Euclidean Jordan algebra V: $\Omega = Int\{x^2 ; x \in V\}.$

• symmetric cone is $\underbrace{irreducible}_{\longrightarrow} \iff$ corresponding EJA is $\underbrace{simple}_{\longrightarrow}$

Example. $V = \operatorname{Sym}(r, \mathbb{R})$

- Jordan product \circ is given by $x \circ y := \frac{1}{2}(xy + yx)$.
- clan product \triangle is given by $x \triangle y = \underline{x} y + y^{t}(\underline{x})$,

where for $x = (x_{ij}) \in \text{Sym}(r, \mathbb{R})$, we set $\underline{x} :=$

$$y^{t}(\underline{x}),$$

 $\underline{x} := \begin{pmatrix} \frac{1}{2}x_{11} & 0 \\ x_{21} & \frac{1}{2}x_{22} \\ \vdots & \ddots & \ddots \\ x_{r1} & \cdots & x_{r,r-1} & \frac{1}{2}x_{rr} \end{pmatrix}$

.

Note $x = \underline{x} + {}^{t}(\underline{x})$.

classification

of irreducible symmetric cones \iff of simple EJA

•
$$\Omega = \operatorname{Sym}(r, \mathbb{R})^{++} \subset V = \operatorname{Sym}(r, \mathbb{R})$$

• $\Omega = \operatorname{Herm}(r, \mathbb{C})^{++} \subset V = \operatorname{Herm}(r, \mathbb{C})$
• $\Omega = \operatorname{Herm}(r, \mathbb{H})^{++} \subset V = \operatorname{Herm}(r, \mathbb{H})$
• $\Omega = \operatorname{Herm}(3, \mathbb{O})^{++} \subset V = \operatorname{Herm}(3, \mathbb{O})$

- $\Omega = \Lambda_n$ (*n*-dim. Lorentz cone) $\subset V = \mathbb{R}^n$: linear part of Clifford algebra
- Non-symm. homogeneous open convex cones (HOCC) appear from dimension 5.
- In dim. ≥ 11 , \exists mutually linearly inequivalent HOCC with a continuous parameter.
- In dim. \leq 10, only finitely many irreducible HOCC exist up to linearly equiv.

— Classification by Kaneyuki–Tsuji ('74)

- concrete realizations up to 7-dim.

- Methods to realize general HOCC by real symmetric matrices
 - (1) By Ishi
 - (2) By Yamasaki–N. (more direct than (1); preprint just finished a few days ago)
 - (2) obtains realizations of 8, 9, 10-dim. HOCC left unrealized by K.–T.

Basic relative invariants

Ω: HOCC ⊂ V, GL(Ω): the linear automorphism group of Ω. ∃H: a split solvable ⊂ GL(Ω) s.t. $H \curvearrowright Ω$ simply transitively

• a function f on Ω is relatively invariant (w.r.t. H) $\stackrel{\text{def}}{\iff} \exists \chi$: 1-dim. rep of H s.t. $f(hx) = \chi(h)f(x) \ (h \in H, x \in \Omega)$.

-Theorem [Ishi 2001]

$$\exists \Delta_1, \ldots, \Delta_r \ (r := \operatorname{rank}(\Omega)) : \underline{\text{irreducible}} \text{ relat. inv. polynomial functions on } V$$

s.t. any relat. inv. polynomial function P on V is uniquely written as
 $P(x) = c \Delta_1(x)^{m_1} \cdots \Delta_r(x)^{m_r} \quad (c = \text{const.}, \ (m_1, \ldots, m_r) \in \mathbb{Z}^r_{\geq 0}).$

• $\Delta_1(x), \ldots, \Delta_r(x)$: the basic relative invariants associated to Ω

Example. When $V = \text{Sym}(r, \mathbb{R})$,

 $\Delta_k(x)$ is the k-th principal minor of $x \in V$ taken from the upper-left corner (also can be taken from the lower-right corner)

• general EJA: Fix a Jordan frame c_1, \ldots, c_r

(complete system of orthogonal primitive idempotents)

- \rightsquigarrow JA principal minors $\Delta_1(x), \ldots, \Delta_r(x)$ are the basic relative invariants. In $V = \text{Sym}(r, \mathbb{R})$,
 - $c_k := E_{kk} \ (k = 1, ..., r) \implies \Delta_k(x)$ is from the upper-left corner $c_k := E_{r-k+1,r-k+1} \ (k = 1, ..., r) \implies \Delta_k(x)$ is from the lower-right corner.

In general, suppose HOCC $\Omega \subset V$ with clan structure of V.

Theorem [Ishi-N. 2008] $R(x)y := y \bigtriangleup x$: the right multiplication operator by x in V \implies the irreducible factors of Det R(x) coincide with $\Delta_1(x), \ldots, \Delta_r(x)$.

-Problem

Let us put $\operatorname{Det} R(x) = \Delta_1(x)^{n_1} \Delta_2(x)^{n_2} \cdots \Delta_r(x)^{n_r}$. Then express the positive integers n_1, \ldots, n_r in terms of the constants related to the clan V.

 $\boldsymbol{n} := (n_1, \ldots, n_r)$ is called the basic index of V.

Example. If V is a simple JA, we have n = (d, ..., d, 1), where $d := \text{common dim. of the "off-diagonals" } V_{kj} (j < k)$. $\text{Sym}(r, \mathbb{R}) : d = 1$, $\text{Herm}(r, \mathbb{K}) (\mathbb{K} = \mathbb{C}, \mathbb{H}, \mathbb{O}) : d = \dim_{\mathbb{R}} \mathbb{K} \text{ (only } r = 3 \text{ occurs when } \mathbb{K} = \mathbb{O})$ if $\Omega = \Lambda_n$, the Lorentz cone in \mathbb{R}^n $(n \ge 3)$, then r = 2, d = n - 2. • For general clan V, the result is due to H. Nakashima (preprint, 2013).

 $\mathbf{n} = \mathbf{m}\sigma^{-1}$

$$V = \begin{pmatrix} \mathbb{R} & V_{21} & \cdots & V_{r-1,1} & V_{r1} \\ V_{21} & \mathbb{R} & & \vdots \\ \vdots & & \ddots & & \vdots \\ V_{r-1,1} & & \mathbb{R} & V_{r,r-1} \\ V_{r1} & \cdots & \cdots & V_{r,r-1} & \mathbb{R} \end{pmatrix}$$
: the normal decomposition of V .

Let
$$m_k := 1 + \sum_{l > k} \dim V_{lk}$$
, and put $m := (m_1, ..., m_r)$.

 σ is the multiplier matrix of V

 $\stackrel{\text{def}}{\iff}$ $r \times r$ -matrix obtained by arranging the parameters of the 1-dim. rep. corresponding to $\Delta_1(x), \ldots, \Delta_r(x)$.

- If V is a simple EJA, then $\sigma = \begin{pmatrix} 1 & 0 \\ \vdots & \\ 1 & \cdots & 1 \end{pmatrix}$.
- In general, σ is a unipotent matrix with non-negative interger entries.

Defining a clan from representations of a EJA

V is a EJA with unit element e_0 , and E is a real vector space with $\langle \cdot | \cdot \rangle_E$.

$$\begin{array}{l} \hline \text{Definition} \\ \text{A linear map } \varphi: V \to \operatorname{End}(E) \text{ is a selfadjoint representation of } V \\ & \underset{(2) \varphi(xy) = \frac{1}{2} (\varphi(x)\varphi(y) + \varphi(y)\varphi(x)), \quad \varphi(e_0) = I \text{ if } \varphi \neq 0. \end{array} \end{array}$$

•
$$V = \operatorname{Herm}(3, \mathbb{O}) \implies \varphi = 0$$

•
$$V = \operatorname{Herm}(r, \mathbb{K}) \ (\mathbb{K} = \mathbb{R}, \mathbb{C}, \mathbb{H})$$

 $\implies E = \operatorname{Mat}(r \times p, \mathbb{K}), \ \varphi(x)\xi = x\xi \ (x \in V, \xi \in E)$

• V: Lorentzian $\implies V = \mathbb{R}e_0 \oplus W$, where (W, B) is a Euclidean VS. JA representation of $V \rightleftharpoons$ Clifford algebra representation of Cl(W)(Cl(W): Clifford algebra with $w^2 = B(w, w)$) In fact, $V \hookrightarrow Cl(W)$

$$c_1, \ldots, c_r$$
: Jordan frame of V. Then $V = \begin{pmatrix} \mathbb{R}c_1 & V_{21} & \cdots & V_{r-1,1} & V_{r1} \\ V_{21} & \mathbb{R}c_2 & & \vdots \\ \vdots & & \ddots & & \vdots \\ V_{r-1,1} & & \mathbb{R}c_{r-1} & V_{r,r-1} \\ V_{r1} & \cdots & \cdots & V_{r,r-1} & \mathbb{R}c_r \end{pmatrix}$

 (φ, E) is a selfadjoint representation of V with dim E > 0. $\rightsquigarrow \varphi(c_1), \ldots, \varphi(c_r)$ are complete system of orthogonal projections of equal rank.

• the lower triangular part $\underline{\varphi}(x)$ of $\varphi(x)$ is defined as $\underline{\varphi}(x) := \frac{1}{2} \sum_{i} \lambda_i \varphi(c_i) + \sum_{j < k} \varphi(c_k) \varphi(x_{kj}) \varphi(c_j) \quad \left(x = \sum_{i} \lambda_i c_i + \sum_{j < k} x_{kj}\right).$ Then, $\underline{\varphi}(x) + \underline{\varphi}(x)^* = \varphi(x).$

-Proposition-

 φ is also a clan representation of V: $\varphi(x\bigtriangleup y)=\underline{\varphi}(x)\varphi(y)+\varphi(y)\underline{\varphi}(x)^* \qquad (x,y\in V).$

• the symmetric bilinear map $Q : E \times E \to V$ associated to φ : $\langle \varphi(x)\xi | \eta \rangle_E = \langle Q(\xi,\eta) | x \rangle \qquad (x \in V, \xi, \eta \in E).$

• Define a product \triangle in $V_E := E \oplus V$ by

 $(\xi+x)\bigtriangleup(\eta+y):=\underline{\varphi}(x)\eta+(Q(\xi,\eta)+x\bigtriangleup y) \qquad (x,y\in V,\ \xi,\eta\in E).$

-Theorem

 (V_E, \triangle) is a clan, and as an admissible linear form we take

$$s'(\xi + x) := \operatorname{Tr} L(x) \qquad (\xi \in E, \ x \in V).$$

- V_E does not have unit element.
 - :.) If $\eta_0 + y_0$ is a unit element, then taking $0 \neq \xi \in E$, we have a contradiction $\xi + 0 = (\xi + 0) \bigtriangleup (\eta_0 + y_0) = 0 + Q(\xi, \eta_0).$
- The homogeneous convex domain corresponding to V_E is the following real Siegel domain defined by

$$D(\Omega, Q) = \{\xi + x \; ; \; x - \frac{1}{2}Q(\xi, \xi) \in \Omega\}.$$

Adjoining the unit element e to V_E , we have $V_E^0 := \mathbb{R}e \oplus V_E$.

Put $u := e - e_0$ (recall e_0 is the unit element of V), we have $V_E^0 = \mathbb{R}u \oplus E \oplus V$. The product is written as

$$\begin{split} (\lambda u + \xi + x) \bigtriangleup (\mu u + \eta + y) &= (\lambda \mu) u + (\mu \xi + \frac{1}{2}\lambda \eta + \underline{\varphi}(x)\eta) + (Q(\xi, \eta) + x \bigtriangleup y) \\ (\lambda, \mu \in \mathbb{R}, \, \xi, \eta \in E \text{ and } x, y \in V). \end{split}$$

• V_E^0 may be imaged as



• Let Ω^0 be the HOCC corresponding to V_E^0 .

ullet Description of Ω^0

$$\Omega^0 = \left\{ \lambda u + \xi + x \in V_E^0 ; \ \lambda > 0, \ \lambda x - \frac{1}{2}Q(\xi,\xi) \in \Omega \right\}.$$

If you cut Ω^0 by the hyperplane $\lambda = 1$, then the Siegel domain $D(\Omega, Q)$ appears as the cross-section.



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Basic relative invariants associated to Ω^0

Let V be a EJA, and $\varphi: V \to \operatorname{Sym}(E)$ a selfadjoint representation of V.

-Definition

 φ is regular $\stackrel{\text{def}}{\iff} \exists \xi_0 \in E \text{ s.t. } Q(\xi_0, \xi_0) = e_0 \text{ (the unit element of } V \text{).}$

In what follows let $V = \operatorname{Herm}(r, \mathbb{K}) \ (r \ge 3; \mathbb{K} = \mathbb{R}, \mathbb{C}, \mathbb{H})$. Then

 $E = \operatorname{Mat}(r \times p, \mathbb{K}), \quad \varphi(x)\xi = x\xi \ (x \in V, \ \xi \in E), \quad Q(\xi, \eta) = \frac{1}{2}(\xi\eta^* + \eta\xi^*)$

Fact: φ is regular $\iff p \ge r$ (*i.e.*, $E = \square$ or $E = \square$).

 $V_E^0 = \mathbb{R}u \oplus E \oplus V \ni \lambda u + \xi + x =: v, \Delta_k(x): k$ -th principal minor (upper-left)

-Theorem

If φ is regular , then the basic relative invariants associated to Ω^0 are

$$\Delta_0^0(v) = \lambda, \quad \Delta_j^0(v) = \Delta_j(\lambda x - \frac{1}{2}\xi\xi^*) \ (j = 1, \dots, r).$$

• If φ is not regular (p < r), then $\Delta_j(\xi\xi^*) = 0$ (j = p + 1, ..., r) \implies For such j, the polynomial $\Delta_j(\lambda x - \frac{1}{2}\xi\xi^*)$ is <u>not</u> irreducible

 \implies at least should be $\lambda^{-(j-p)}\Delta_j(\lambda x - \frac{1}{2}\xi\xi^*) \longleftarrow I$ do not like this.

-Theorem

If p < r, then the basic relative invariants associated to Ω^0 are

$$\begin{cases} \Delta_0^0(v) = \lambda, \\ \Delta_j^0(v) = \Delta_j(\lambda x - \frac{1}{2}\xi\xi^*) & (j = 1, \dots, p), \\ \Delta_j^0(v) = \det^{(p+j)} \begin{pmatrix} \lambda I_p & \frac{1}{\sqrt{2}}\xi^* \\ \frac{1}{\sqrt{2}}\xi & x \end{pmatrix} & (j = p+1, \dots, r) \end{cases}$$

Here, $det^{(p+j)}X$ is the upper-left (p+j)-th principal minor of X. Moreover if $\mathbb{K} = \mathbb{H}$, it should be taken as the Jordan algebra determinant.

Dual cone $(\Omega^0)^*$, and the associated basic relative invariants

Introduce an inner product in $V_E^0 = \mathbb{R}u \oplus E \oplus V$ by

$$\langle \lambda u + \xi + x \,|\, \lambda' u + \xi' + x' \,\rangle^0 = \lambda \lambda' + \langle \xi \,|\, \xi' \,\rangle_E + \langle x \,|\, x' \,\rangle.$$

Let $(\Omega^0)^*$ be the dual cone of Ω^0 w.r.t this inner product:

 $\left(\Omega^{0}\right)^{*} := \left\{ v \in V_{E}^{0} ; \langle v | v' \rangle^{0} > 0 \ \forall v' \in \overline{(\Omega^{0})} \setminus \{0\} \right\}.$

• $v \bigtriangledown v' = {}^{t}L^{0}(v)v'$ defines a clan structure in V_{E}^{0} ($L^{0}(v)$ is the left-multiplication operator in V_{E}^{0}).

–Proposition

$$\left(\Omega^{0}\right)^{*} = \left\{ v = \lambda u + \xi + x \; ; \; x \in \Omega, \; \lambda > \frac{1}{2} \langle \varphi(x)^{-1} \xi \, | \, \xi \, \rangle_{E} \right\}.$$

Remark. The proposition says that $(\Omega^0)^*$ coincides with what Rothaus ('66) called *the extension of* Ω *by the representation* φ .

 $\Delta_1^*(x), \ldots, \Delta_r^*(x)$: JA principal minors associated to c_r, \ldots, c_1 (we have reversed the order of the original Jordan frame)

• In the case $Sym(r, \mathbb{R})$, we just take the lower-right princial minors.

Theorem

The basic relative invarants $P_j(v)$ associated to $(\Omega^0)^*$ are

$$P_j(\lambda u + \xi + x) = \Delta_j^*(x) \qquad (j = 1, \dots, r),$$
$$P_{r+1}(\lambda u + \xi + x) = \lambda \det x - \frac{1}{2} \langle \varphi({}^{co}x)\xi | \xi \rangle.$$

- If $x \in V$ is invertible, then ${}^{co}x := (\det x)x^{-1}$.
- In general ${}^{co}\!x$ is a polynomial map of degree r-1 that is defined through the JA version of the Cayley–Hamilton theorem.
- $\deg P_j = j \ (j = 1, \dots, r, r + 1).$

The previous theorem systematically provides examples of HOCC such that the degrees of the asociated basic relative invariants are

 $1, 2, \ldots, r = \operatorname{rank}(\Omega)$

even for non-symmetric cones.

This generalizes an example given in Ishi–N. [2008].

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-Problem
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Let Ω be a HOCC of rank r

Then Ω is a symmetric cone

 \iff the degrees of the basic relative invariants associted to Ω , and the degrees of the basic relative invariants associted to Ω^* are both $1, 2, \ldots, r$.

T. Yamasaki wrote up a paper very recently in the affirmative. (I'm currently checking his first draft . . .)

Another project: Starting with a clan rep. instead of JA rep.
 H. Nakashima, preprint (submitted 1 month ago).